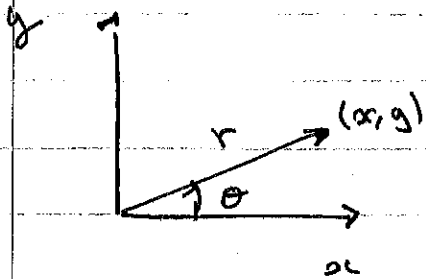
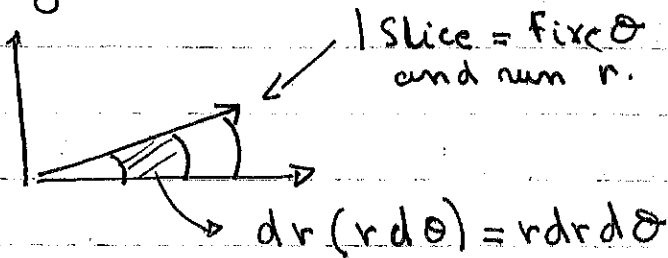


double integrals - polar coordinates
change of variables - Jacobians.



$$x = r \cos \theta$$

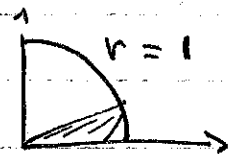
$$y = r \sin \theta$$



$dA = r dr d\theta$ in polar coordinate.

Example 1:

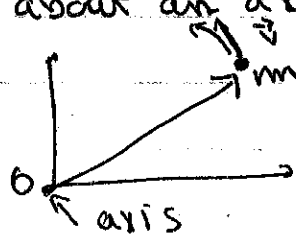
$$I = \iint (1 - x^2 - y^2) dA$$



$$I = \int_0^{\pi/2} d\theta \int_0^1 (1 - r^2) r dr \quad \text{with } dA = r d\theta dr$$

$$I = \int_0^{\pi/2} d\theta \left[\frac{r^2}{2} - \frac{r^4}{4} \right]_0^1 = \frac{\pi}{8} \quad \text{easier this way.}$$

Example 2: moment of inertia = resistance to rotation motion \Rightarrow how hard it is to rotate about an axis.



point mass

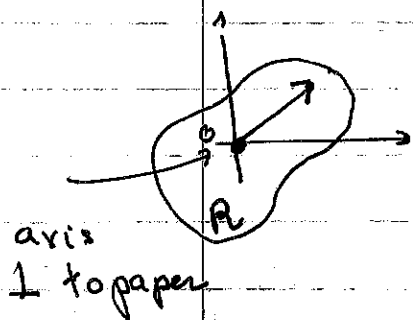
$$v = r\omega$$

$$\text{kinetic energy} = \frac{1}{2} m r^2 \omega^2$$

so moment of

$$\text{inertia for point mass} = m r^2$$

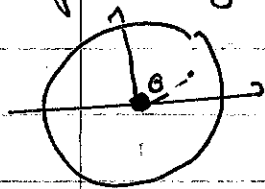
consider a solid with density δ (per surface)



$$I_0 = \int_R r^2 \delta dA$$

moment
of inertia
about O

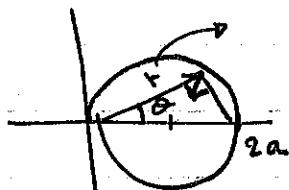
Example: Find the moment of inertia of a disk, spinning about O, radius a. $\delta = \frac{M}{\pi a^2}$



$$\int_0^{2\pi} \int_0^a r^2 r d\theta dr = \int_0^{2\pi} \left[\frac{r^4}{4} \right]_0^a d\theta$$

$$= \frac{2M a^4}{4} = \frac{a^4 M}{2}$$

Example: Now the axis is placed at the edge of the disk.



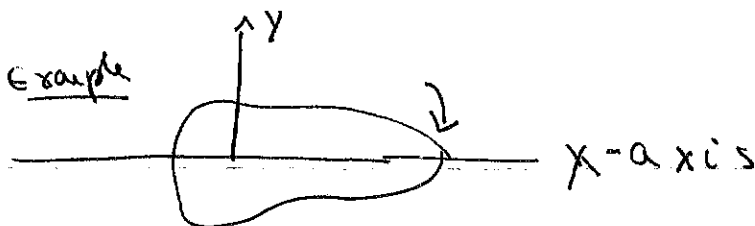
if O is fixed,

r runs from 0 to $2a \cos \theta$

$$\int_{-\pi/2}^{\pi/2} \int_0^{2a \cos \theta} r^3 dr d\theta = \int_{-\pi/2}^{\pi/2} \left[\frac{r^4}{4} \right]_0^{2a \cos \theta} d\theta = \int_{-\pi/2}^{\pi/2} \frac{16a^4 \cos^4 \theta}{4} d\theta$$

$$= 4a^4 \int_{-\pi/2}^{\pi/2} \cos^4 \theta d\theta = \boxed{\frac{3}{2} \pi a^4}$$

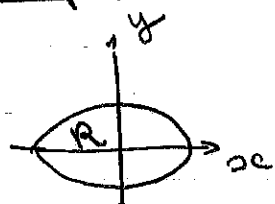
Example



$$I = \iint y^2 \delta dA.$$

change of variables - Jacobians

Example 1 Find area of an ellipse $\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = 1$



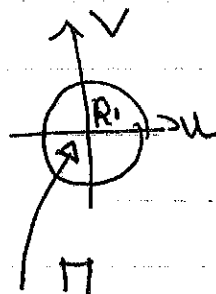
$$A = \iint_R dx dy$$

$$u = \frac{x}{a} \Rightarrow dx = du a$$

$$v = \frac{y}{b} \Rightarrow dy = dv b$$

$$A = ab \iint_{u^2 + v^2 \leq 1} du dv$$

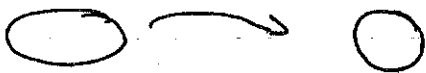
the region becomes a circle of radius 1



so $A = ab \pi$.

the scaling factor between R and R_1

is ab .



Example 2

$$\begin{cases} u = 3x - 2y \\ v = x + y \end{cases}$$

we need linear approximation to find $\Delta u \Delta v$

$$\begin{cases} \Delta u = u_x \Delta x + u_y \Delta y \\ \Delta v = v_x \Delta x + v_y \Delta y \end{cases}$$

$$\text{so } \begin{bmatrix} \Delta u \\ \Delta v \end{bmatrix} = \begin{bmatrix} u_x & u_y \\ v_x & v_y \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$$

linear approximation:

$$\Delta u \Delta v \approx (u_x v_y - u_y v_x) \Delta x \Delta y$$
$$\Delta u \Delta v = \det \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} \Delta x \Delta y$$

$$\text{or } \Delta u \Delta v = \frac{\partial(u, v)}{\partial(x, y)} \Delta x \Delta y$$

$\frac{\partial(u, v)}{\partial(x, y)} \leftarrow \text{Jacobian}$

$$\text{and } \frac{\partial(x, y)}{\partial(u, v)} = \frac{1}{\frac{\partial(u, v)}{\partial(x, y)}}$$

Example 1: polar coordinates.

$$x = r \cos \theta \quad y = r \sin \theta$$
$$\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$$
$$J = r \cos^2 \theta + r \sin^2 \theta = r$$
$$\boxed{\Delta x \Delta y = r \Delta r \Delta \theta}$$

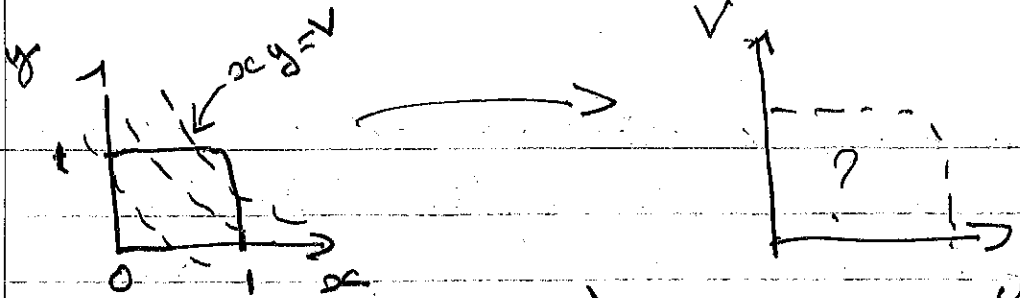
Example 2 compute $\int_0^1 \int_0^1 x^2 y \, dx \, dy$ by changing

variable $\begin{cases} u = x \\ v = y \end{cases}$ $\frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1$

$$\Delta u \Delta v = \Delta x \Delta y \Rightarrow \Delta x \Delta y = \frac{1}{1}$$

$$I = \int \int V \, du \, dv \quad \text{we need to find the bounds.}$$

1st way



if $v = \text{constant}$ or $y = \text{constant} = \text{hyperbola } u$

$0 < v < 1$, along the hyperbola u varies.

if $y=1$, $u=v$ if $x=1$, $u=1$

hyperbola enters
the region

hyperbola leaves
the region

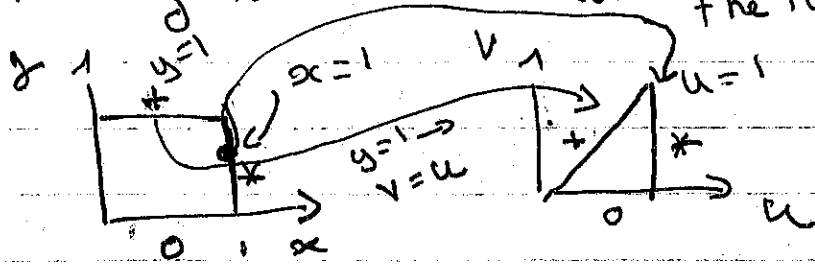
so $v < u < 1$
 $0 < v < 1$

$$I = \int_0^1 \int_v^1 du dv$$

$$I = \int_0^1 v [u]_v^1 dv = \int_0^1 v(1-v) dv$$

$$I = \left[\frac{v^2}{2} - \frac{v^3}{3} \right]_0^1 = \frac{1}{6}$$

2nd way to find bounds: the line $xy=1$ becomes $u=1$



same answer.