

linear 2nd order diff equ.  
homogeneous.

Standard Form:

$$y'' + Ay' + By = 0 \quad (\text{homogeneous form})$$

A and B are real and constant.

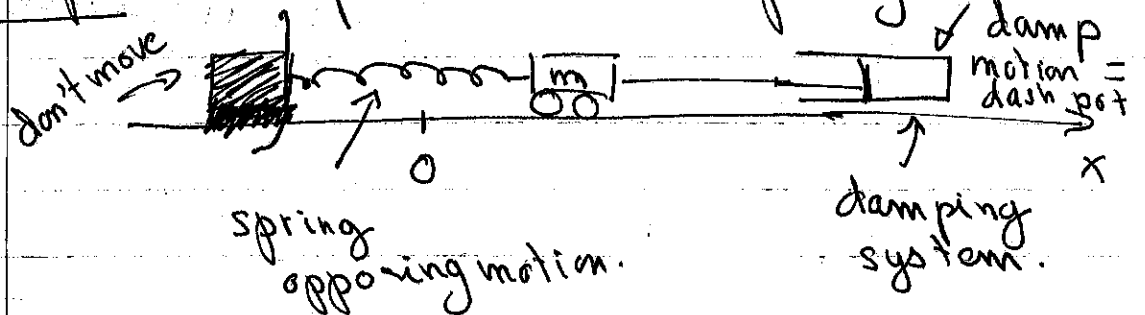
Let's assume the general solution is

$$y = C_1 y_1 + C_2 y_2 \quad \begin{array}{l} y_1 \text{ and } y_2 \\ \text{are independent} \\ (y_1 \neq k y_2) \end{array}$$

$C_1$  and  $C_2$  are arbitrary constant defined by initial conditions.

Note order of equation = # of constant to find.

Example: damped motion of a spring.



Newton

2nd law:

$$m \ddot{x} = -kx - c \dot{x}$$

$-kx$  sp Hookes Law Force applied by spring on mass  
 $-c \dot{x}$  Force applied by damping system = depends on the speed.

$k$  is the spring constant  
 $C$  is the damping constant

the ratio  $k/c$   
will determine  
the damping  
of the motion →  
if ~~the~~ the mass  
will oscillate or no.

we need to find  $y = C_1 y_1 + C_2 y_2$ .

suppose  $y = e^{rt}$  and let's plug it  
in equation:

$$x'' + \frac{C}{m} x' + \frac{k}{m} x = 0$$

$$r^2 e^{rt} + \frac{C}{m} r e^{rt} + \frac{k}{m} e^{rt} = 0$$

$$\boxed{r^2 + \frac{C}{m} r + \frac{k}{m} = 0} \quad \left| \begin{array}{l} \text{this is called the} \\ \text{characteristic} \\ \text{equation.} \end{array} \right.$$

- 3 cases {
- ① roots are real and distinct
  - ② pairs of conjugate numbers
  - ③ real and equal. (double solution)

case 1 we have 2 real solutions  $r_1$  and  $r_2$   
so we have the 2 solutions  $y_1$  and  $y_2$ .

$$y = C_1 e^{r_1 t} + C_2 e^{r_2 t}$$

Example case 1

more damping.

$$r^2 + 4r + 3 = 0$$

$$(r+3)(r+1) = 0$$

$$r = -1 \text{ and } r = -3$$

damping > spring constant

$$y = C_1 e^{-3t} + C_2 e^{-t}$$

$r = -1$   
 $r = -3$

initial conditions.

more m by 1  
released from rest

$$y(0) = 1 \rightarrow 1 = C_1 + C_2$$

$$y'(0) = 0 \rightarrow 0 = -3C_1 - C_2 = 0$$

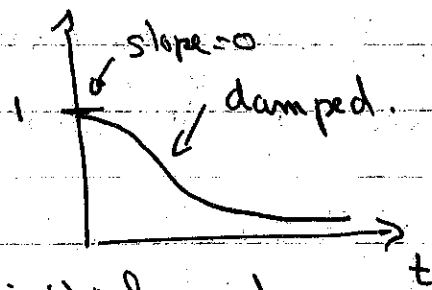

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$$1 = -2C_1 \Rightarrow C_1 = -1/2$$

$$C_2 = 1 - C_1 = 3/2$$

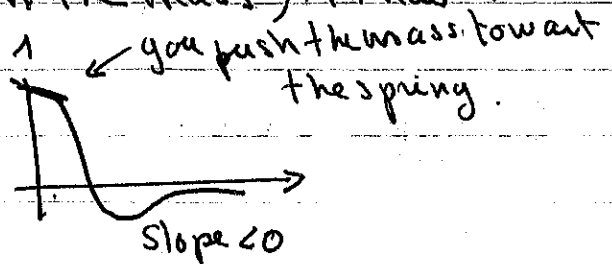
$$y = -\frac{1}{2} e^{-3t} + \frac{3}{2} e^{-t}$$

$y(0) = 1$      $y'(0) = 0 \Rightarrow \text{slope} = 0$  (flat)

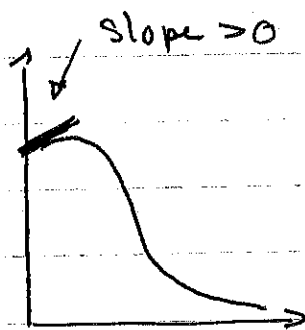


No initial speed.

(if  $y'(0) \neq 0$ , you push the mass, it has time to go back and forth) (in the negative direction.)



If initial speed is positive, you push the mass toward the damping part of the system. The mass can't go back toward the spring.



case 2 the roots are complex  $\alpha = a \pm bi$

so  $\tilde{y}$  <sub>complex</sub> =  $e^{(a+bi)t} = e^{at} e^{ibt}$  How to find the real solution?

$$y_1 = \operatorname{Re}(\tilde{y}) \text{ and } y_2 = \operatorname{Im}(\tilde{y})$$

$$\text{so } y = C_1 e^{at} (\cos bt) + C_2 e^{at} (\sin bt)$$

$$y = e^{at} (C_1 \cos bt + C_2 \sin bt)$$

\* proof if  $u + vi$  is solution of  $y'' + Ay' + By = 0$   
 then  $(u + vi)'' + A(u + vi)' + B(u + vi) = 0$   
 $\Rightarrow u'' + Au' + Bu + i(v'' + Av' + Bv) = 0$   
 $\Rightarrow u'' + Au' + Bu = 0$  and  $v'' + Av' + Bv = 0$   
 so Real part and Imaginary part are solutions.

## Example of case 2



Now damping constant  $<$  spring constant.

$$y'' + 4y' + 5 = 0$$

characteristic equation:  $r^2 + 4r + 5 = 0$

quadratic equation }  $r = \frac{-4 \pm 2i}{2} = -2 \pm i$

let's choose 1 root  $\alpha = -2 + i$   
(you get the same thing if you take  $-2 - i$ )

$$\tilde{y} = e^{\alpha t} e^{it} \Rightarrow y_1 = e^{-2t} \cos t \quad y_2 = e^{-2t} \sin t$$

$$\text{so } y = C_1 e^{-2t} \cos t + C_2 e^{-2t} \sin t$$

$$y(0) = 1 \Rightarrow C_1 = 1$$

$$y'(0) = 0 \Rightarrow C_2 = 2C_1 = 2$$

so  $y = e^{-2t} (\cos t + 2 \sin t)$  } let's add representation of Fresnel to add  $\cos t + 2 \sin t$ .

$$\begin{aligned} \cos t + 2 \sin t &= \cos t + 2 \cos(t - \frac{\pi}{2}) = \cos t + 2 \cos(t - \frac{\pi}{2}) \\ &= \sqrt{5} (e^{it} + 2e^{i(t - \pi/2)}) = \sqrt{5} (e^{it} + 2e^{it} e^{-i\pi/2}) \end{aligned}$$

$$\sqrt{5} e^{it} (1 + 2e^{-i\pi/2})$$

$$= \sqrt{5} e^{it} \sqrt{5} e^{-i\phi}$$

$$= \sqrt{5} e^{i(t - \phi)} = \sqrt{5} \cos(t - \phi)$$

